

Detection of track damage in railway - Train based field test of prototype

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Project purpose

- Reduce manual inspections and humans on the railway track
- Increase safety
- Focusing on railway fatener systems and missing clamps





Automated Maintenance



14.000 km of railway lines93 million clamps



Background

Railway Fastener Inspection by Real-Time Machine Vision

Çağlar Aytekin, Yousef Rezaeitabar, Sedat Dogru, and İlkay Ulusoy



www.vision-systems.com



Fig. 1. (a) Camera and laser source box. (b) Camera and laser source mounted under the track. (c) Schematic of the system.



Background

Problem with visuall inspection



https://www.youtube.com/watch?v=CY3AcSYRyDo





Background





The three most important results

- 1. Successful field tests using a in service locomotive
- 2. Successful identification of missing clamps using ML
- 3. Detection of additional anomalies (Welds, insulation joints etc)





1 Field test







2 Unsupervised machine learning



Supervised



Unsupervised, Anomaly detection

www.infrasweden2030.se

2 Unsupervised machine learning



Unsupervised Machine Learning

3 Additional anomalies

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Unsupervised Machine Learning

Important Learning outcomes

- It is possible to detect fasteners from an in service train at 70 km/h (Theoreticaly 300 km/h)
- Other aspects can also be detected
- ML is a vital part of the solution
- Field tests are difficult to plan and manage. Highly dependedn to scocial parameters and resourse avaialbilities.
- Physical measurement campaigns in the field cost money and is time consuming













Discussion



- What are the key factors for practical Implementation?
 - Engaged individual people in various organisations (IMs) which owns the problem.
 - Social relationships
 - Patience
- How to spread the result to generate innovation?
 - Marketing the result in EU projects for other IMs
 - Utilise the result for other applications like detection of other defects (Surface defects)
 - Interact with other IMs with different problems related to the project result (Track geometry measurement)